

A BCD ADDER

24.06.2011



ex:

$x = 0111$ 7_{10}
 $y = 0101$ 5_{10}

$\underline{\underline{1100}}$

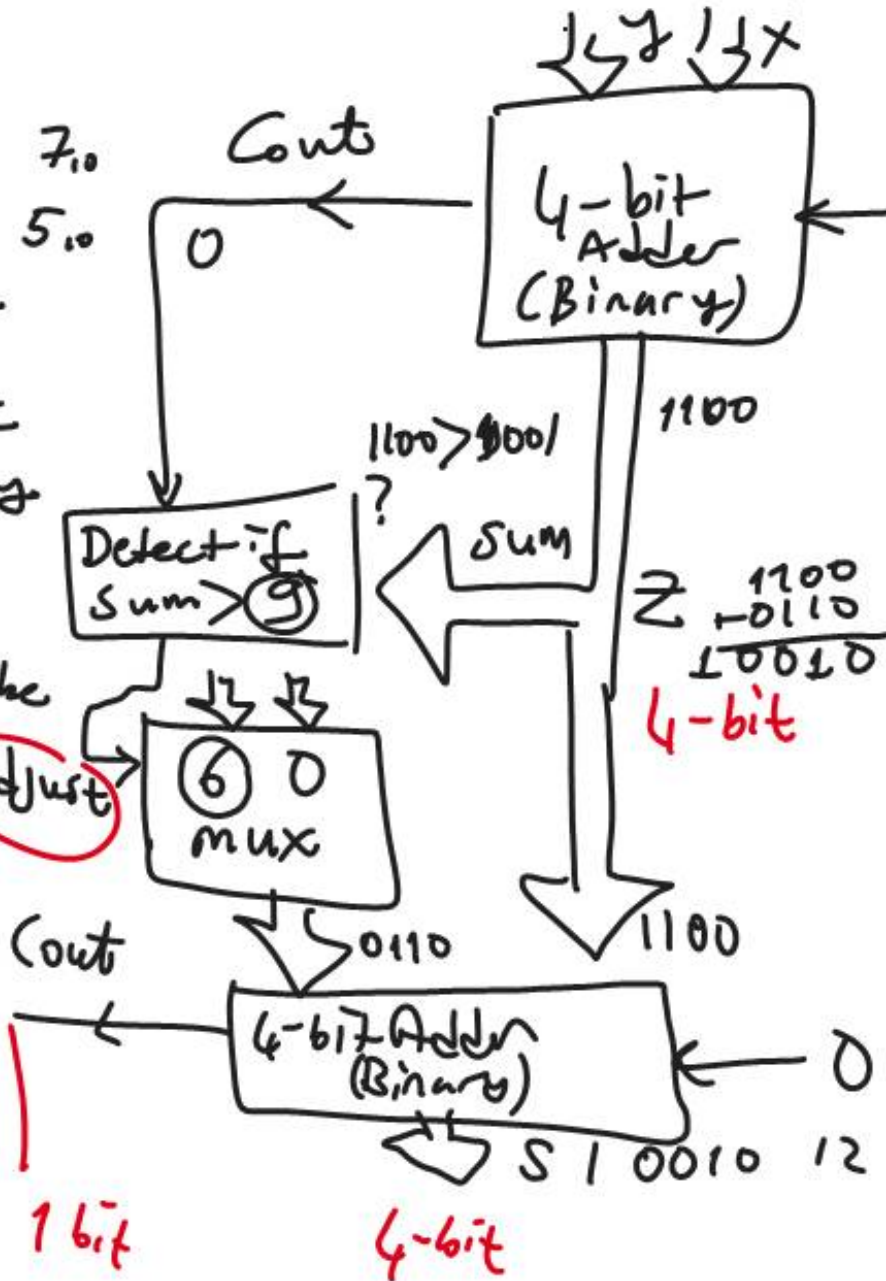
12 binary

1100
 in BCD
 it should be

0001 0000

(12)

Adjust



0 0000

1 0001

2 0010

3 0011

4 0100

5 0101

6 0110

7 0111

8 1000

9 1001

Not defined 10 10

11 11

12 1111

0001 0000

1 0

```
LIBRARY ieee;
USE ieee.std_logic_1164.all;
USE ieee.std_logic_unsigned.all;
```

(This is arithmetic) BCD Adder

```
ENTITY BCD IS
```

```
PORT (X, Y : IN STD_LOGIC_VECTOR(3 DOWN TO 0);
      S : OUT STD_LOGIC_VECTOR(4 DOWN TO 0));
```

```
END BCD;
```

ARCHITECTURE Behavior OF BCD IS

```
SIGNAL z : STD_LOGIC_VECTOR(4 DOWN TO 0);
```

```
SIGNAL ADJUST : STD_LOGIC;
```

```
BEGIN
```

```
z <= ('0' & x + y);
```

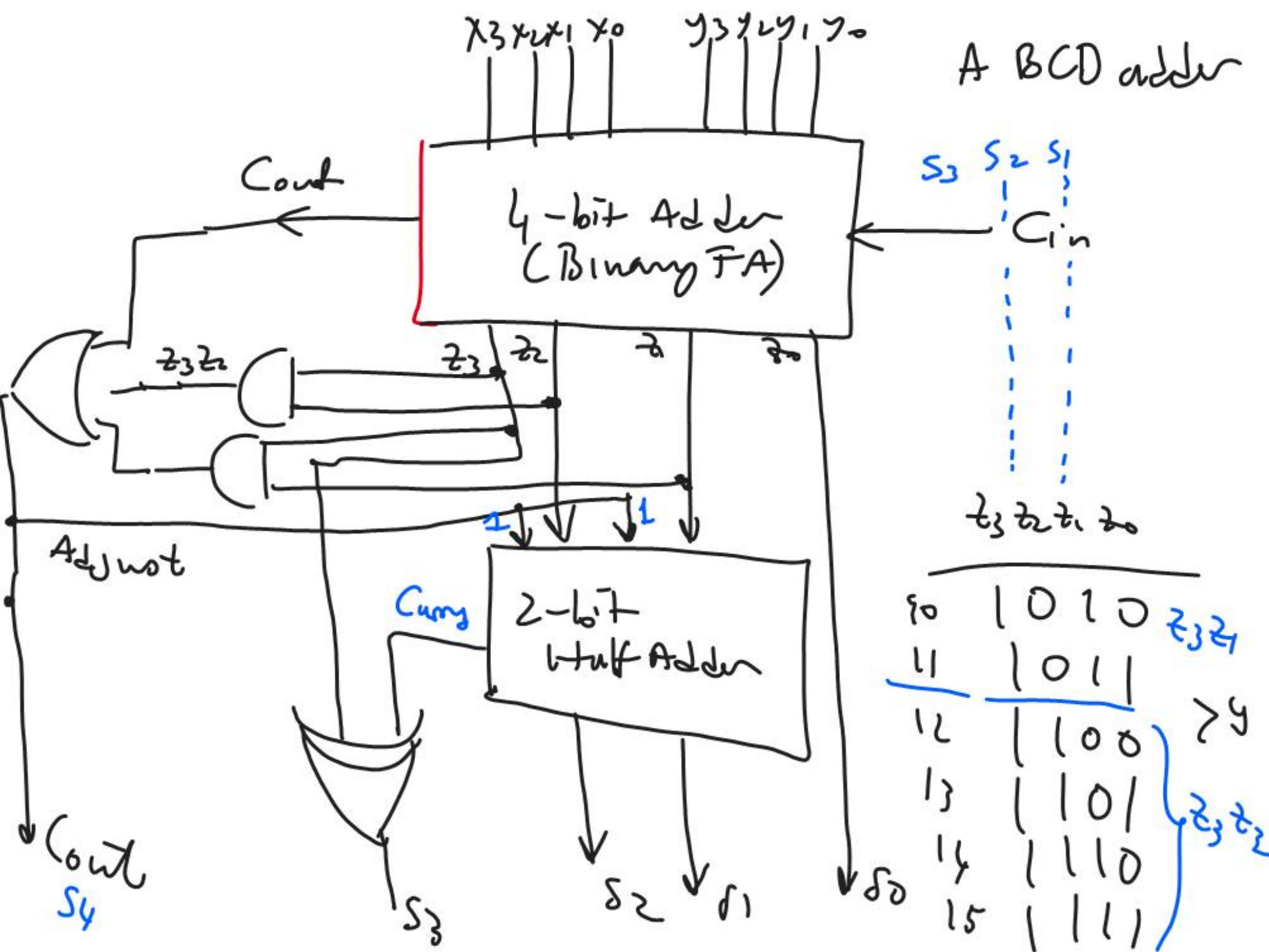
```
ADJUST <= '1' WHEN z > 9 ELSE '0';
```

```
S <= z WHEN (ADJUST = '0') ELSE z + 6;
```

```
END BEHAVIOR;
```

* Be careful
z is a 5-bit number
→ S is a 5-bit number

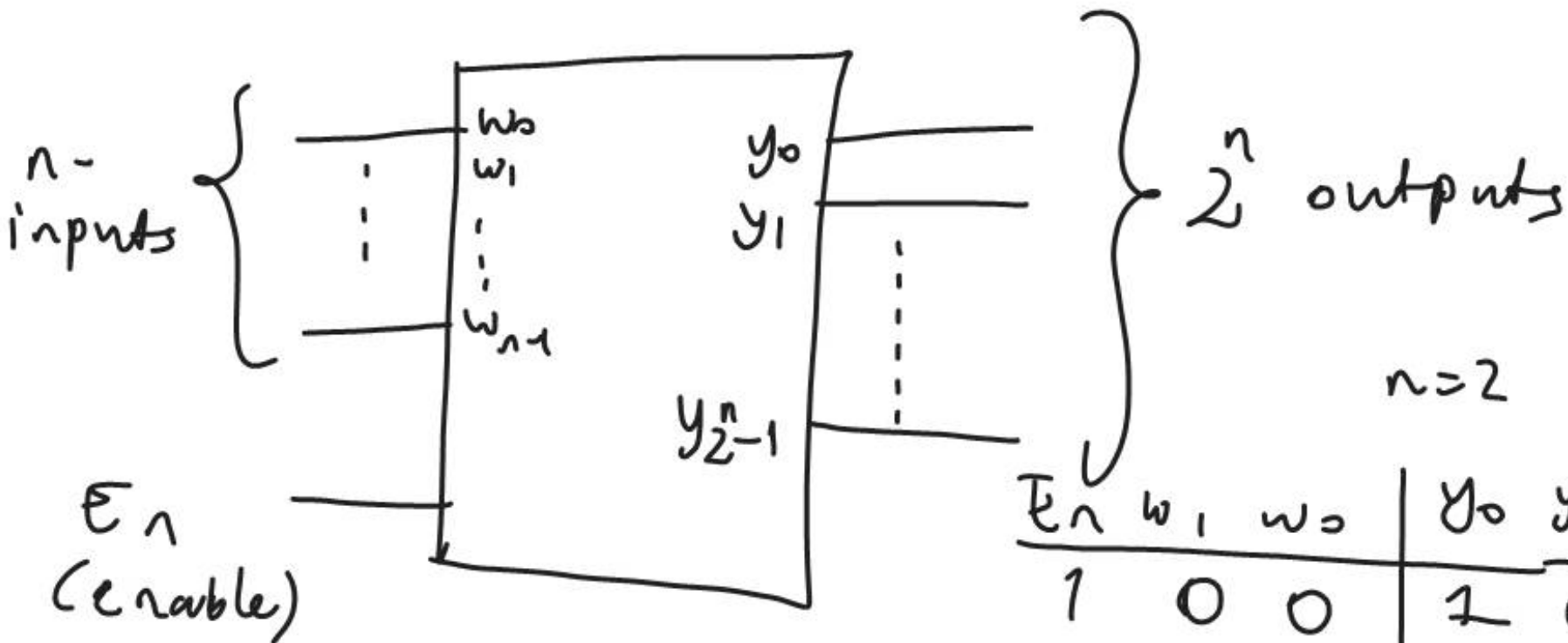
A BCD adder



	z_3	z_2	z_1	z_0
9	1	0	1	0
11	1	0	1	1
12	1	0	0	0
13	1	0	1	1
14	1	1	1	0
15	1	1	1	1

$z_3 z_2$ (bits 9-11)
 $z_3 z_2$ (bits 13-15)

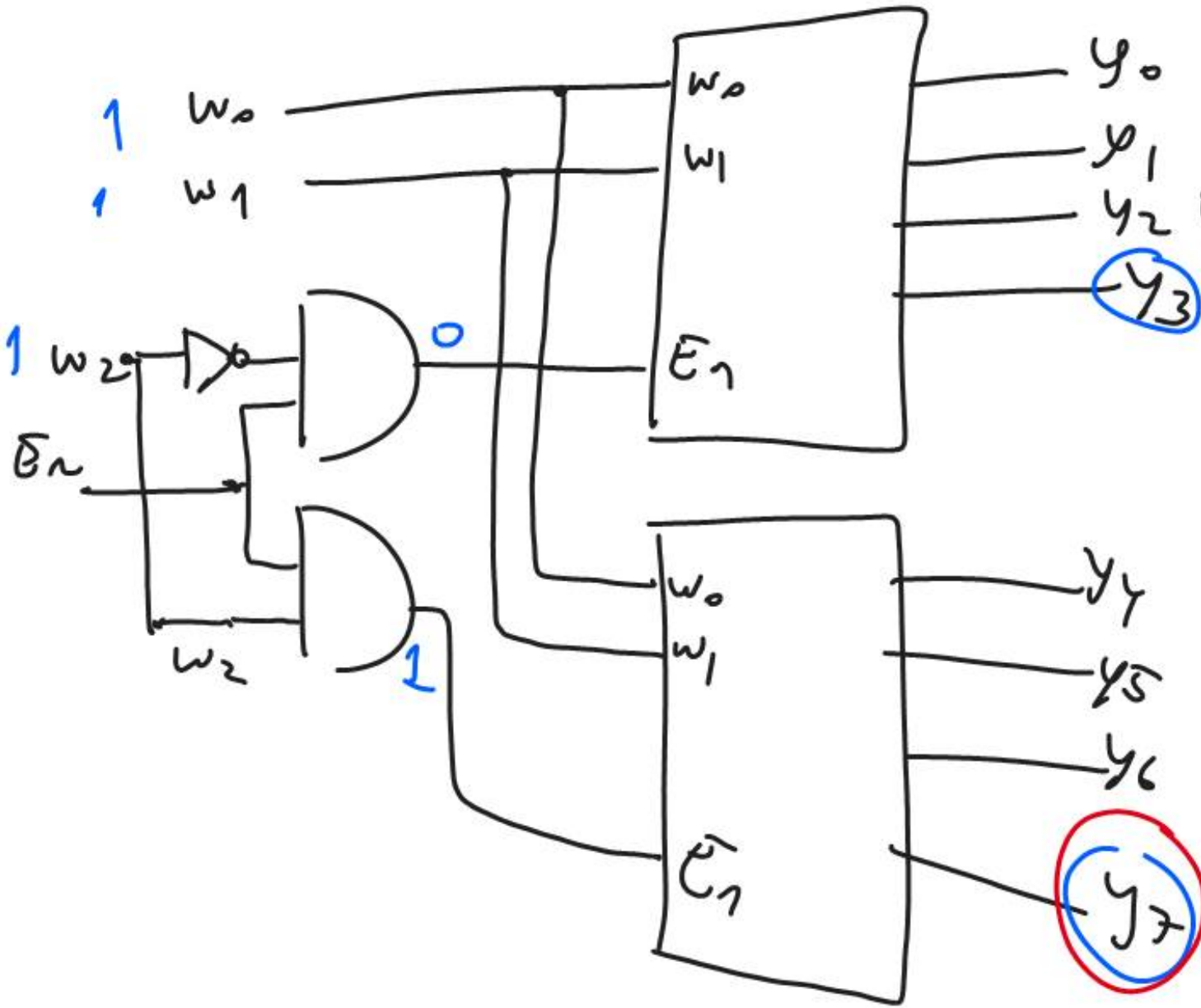
DECODERS



$n=2$

E_n	w_1	w_0	y_0	y_1	y_2	y_3
1	0	0	1	0	0	0
1	0	1	0	1	0	0
1	1	0	0	0	1	0
1	1	1	0	0	0	1
0	X	X	0	0	0	0

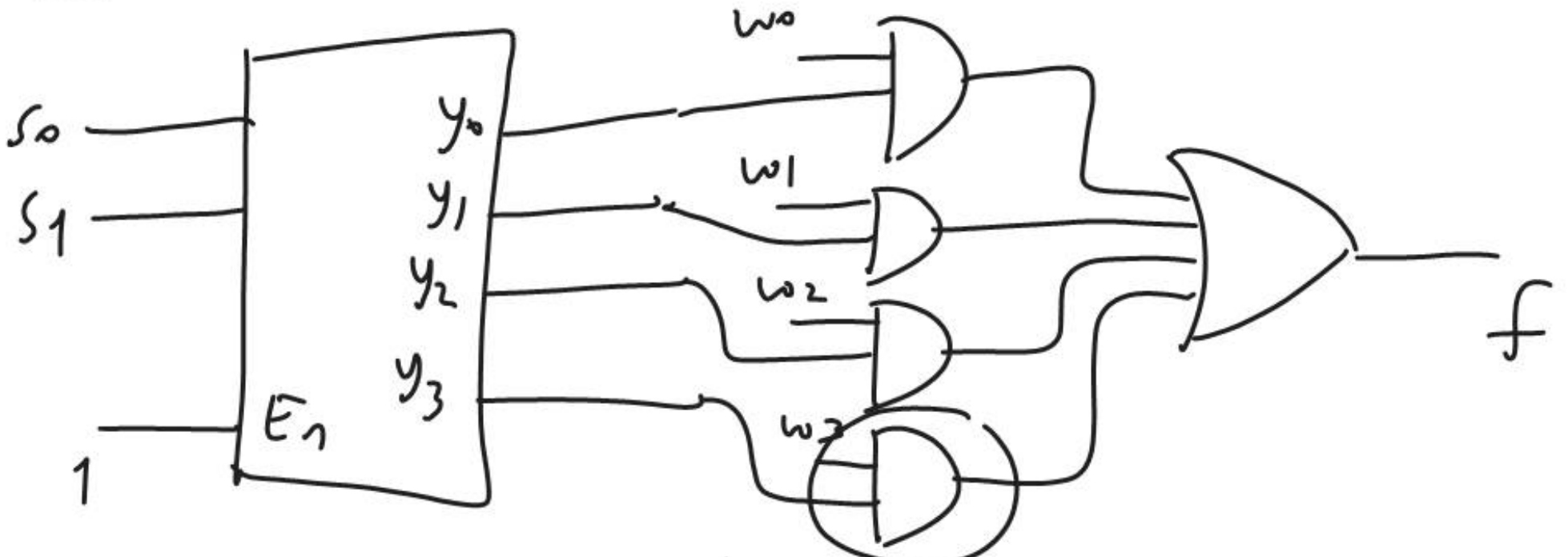
3-to-($2^3=8$) DECODER with 2-4 Decoders



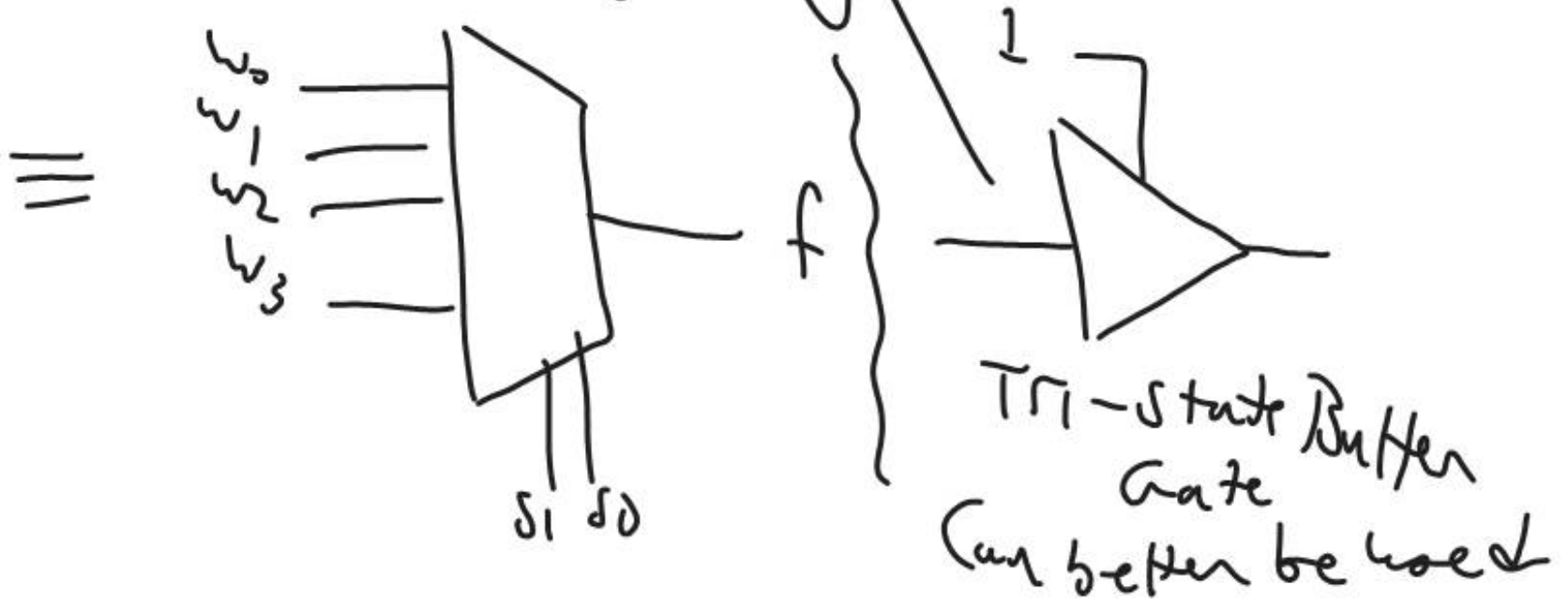
E_n	w_2	w_1	w_0	y_0	y_1	y_2	y_3
1	0	0	0	1	0	0	0
1	0	0	1	0	1	0	0
1	0	1	0	0	0	1	0
1	0	1	1	0	0	0	1
1	1	0	0	0	0	0	0
1	1	0	1	0	0	0	0
1	1	1	0	0	0	0	0
1	1	1	1	0	0	0	0
0	x	x	x	0	0	0	0

is relevant

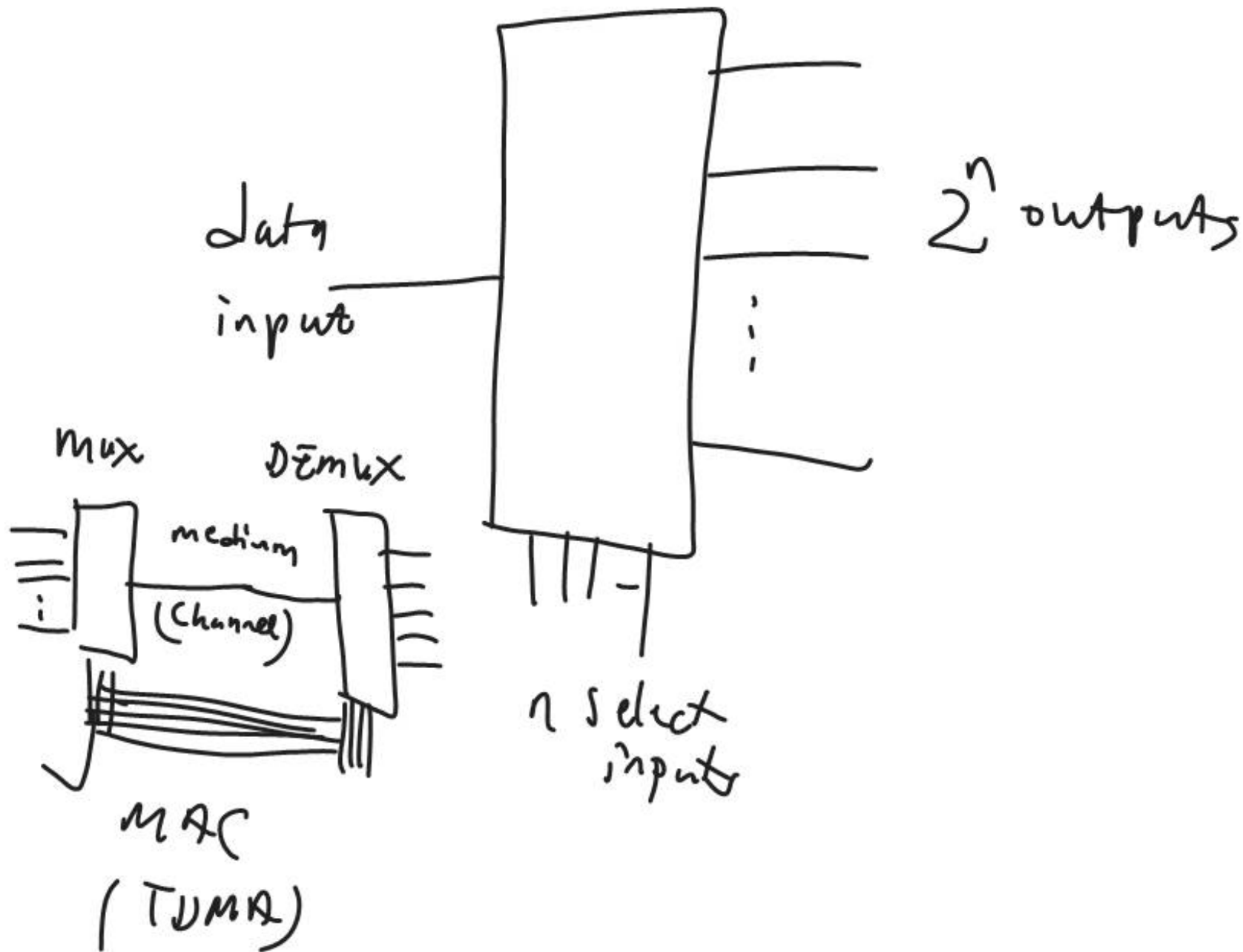
ex



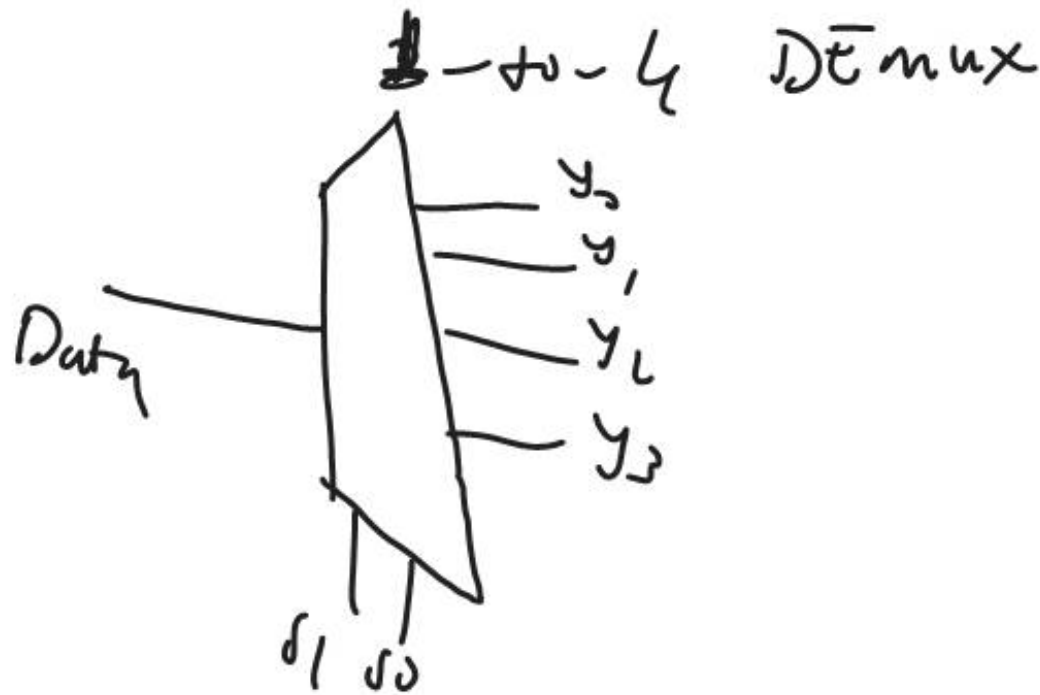
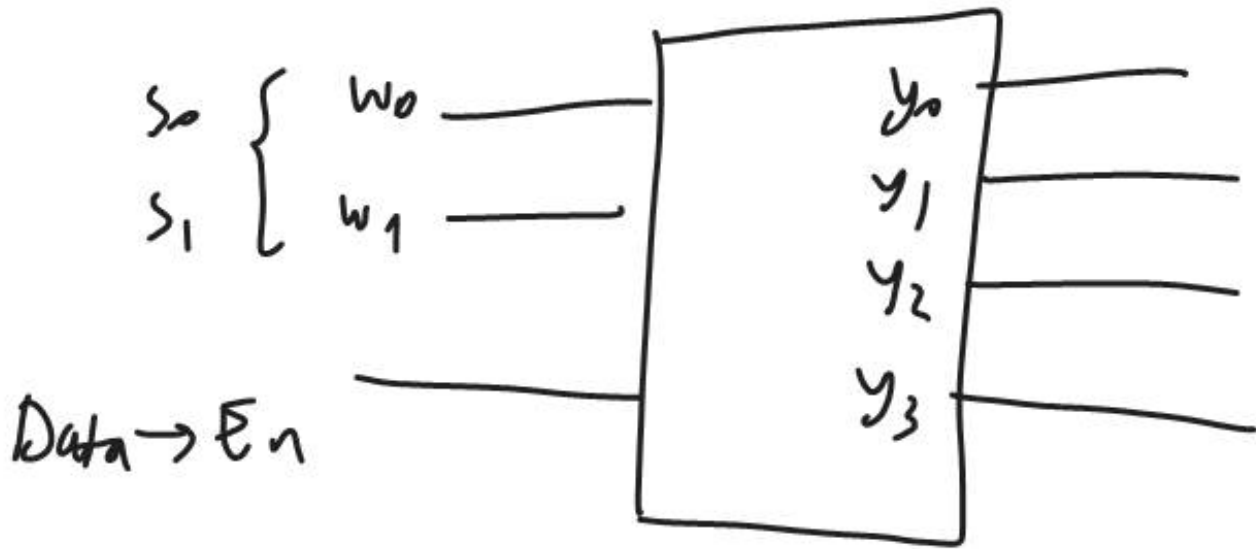
a 4-to-1 mux by using a 2-to-4 Decoder

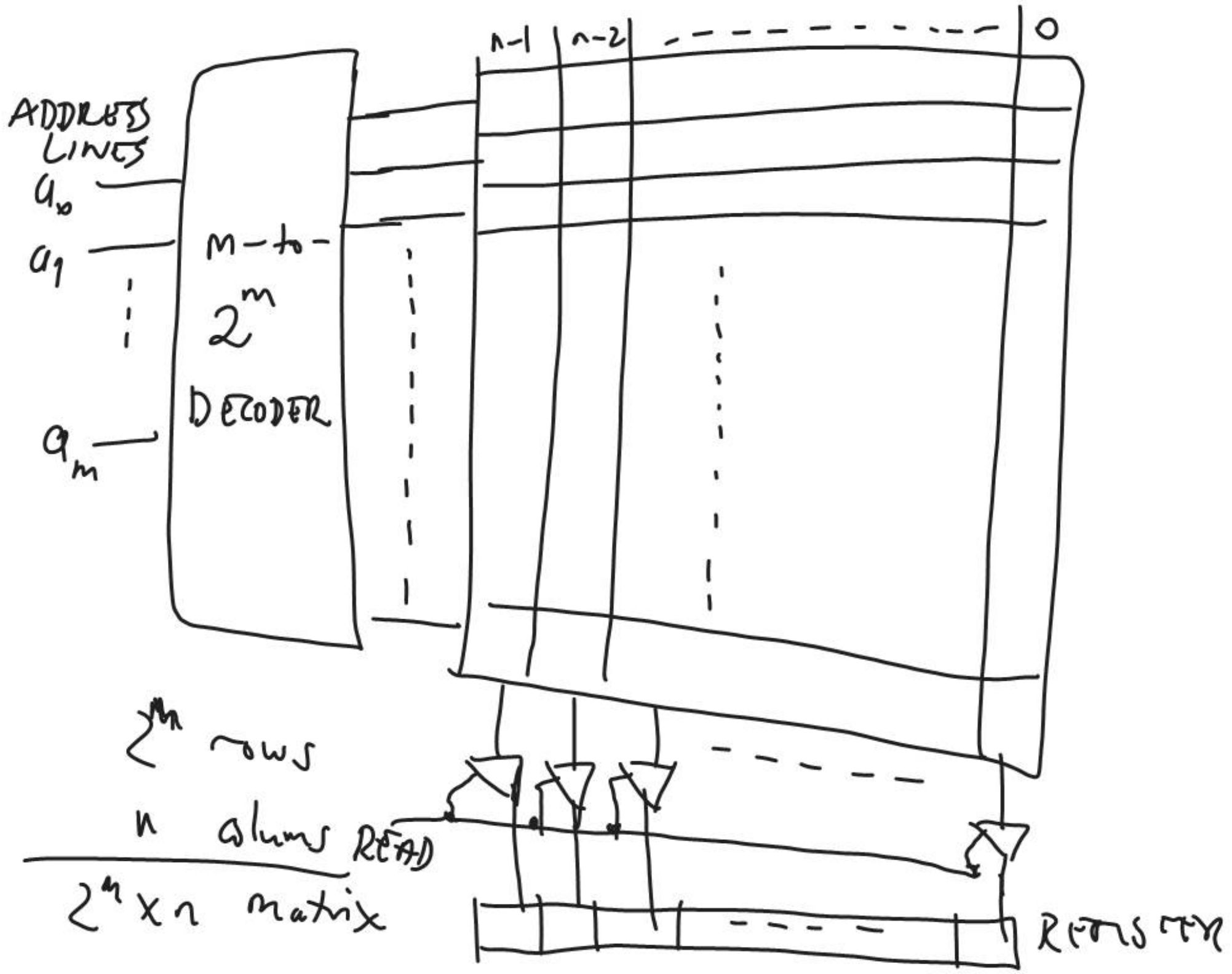


DEMULTIPLEXERS

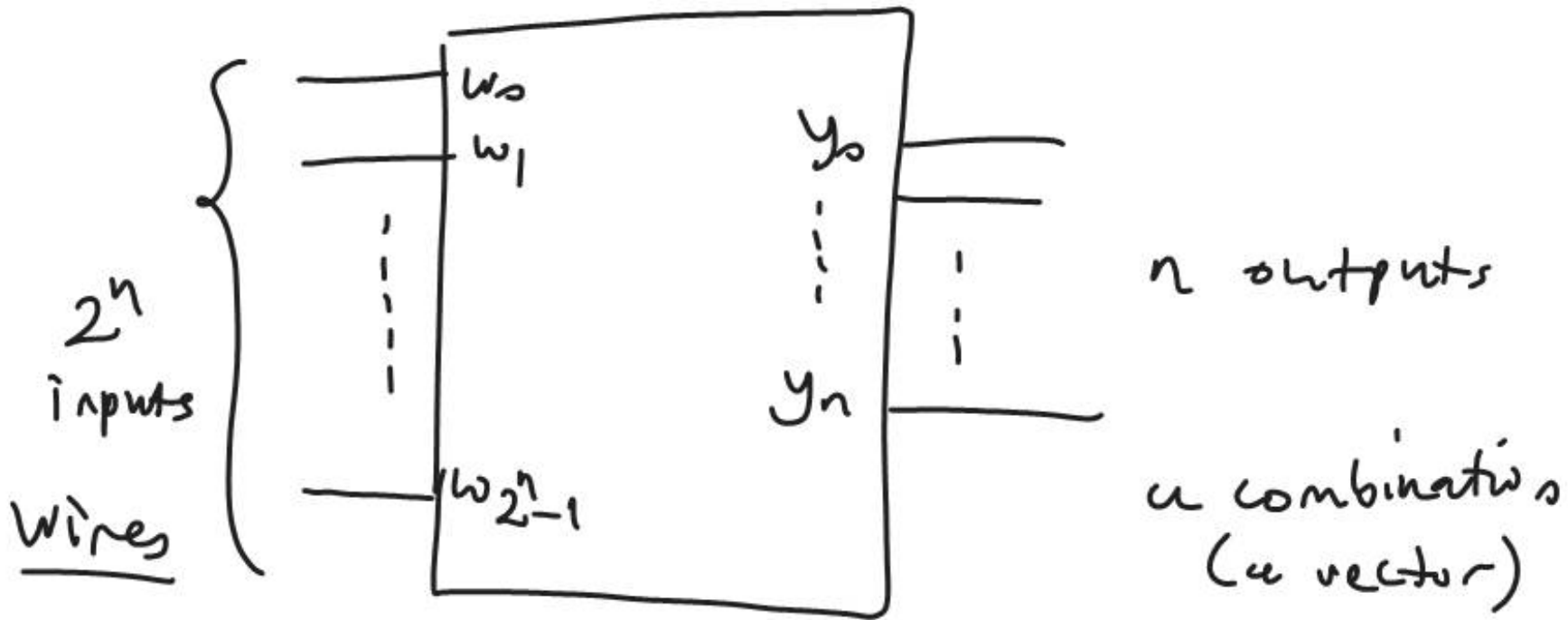


A Decoder can be used as a Demux



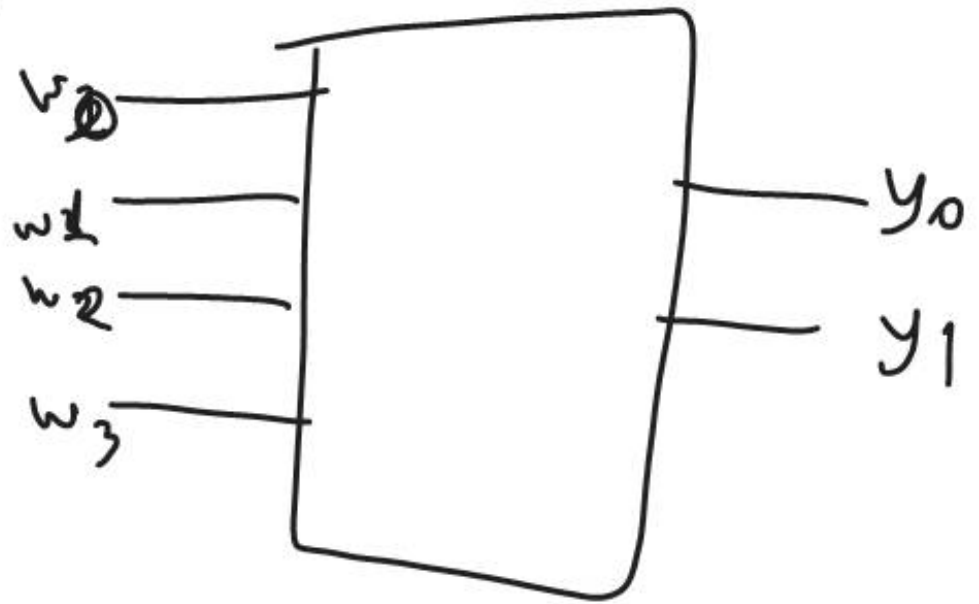


ENCODERS



It provides more compact form.

w_3	w_2	w_1	w_0	y_1	y_0
0	0	0	1	0	0
0	0	1	0	0	1
0	1	0	0	1	0
1	0	0	0	1	1



A 4-to-2 Encoder

more economical or compact representation is provided by an encoder.

A Priority Encoder

3-output functions

w_3 : highest priority

w_0 : lowest

w_3	w_2	w_1	w_0	y_1	y_0	z
0	0	0	0	0	0	0
0	0	0	1	0	0	1
0	0	1	X	0	1	1
0	1	X	X	1	0	1
1	X	X	X	1	1	1

irrelevant

don't care either 0 or 1

intermediate signals

$$\bar{t}_0 = \bar{w}_3 \bar{w}_2 \bar{w}_1 w_0$$

$$\bar{t}_1 = \bar{w}_3 \bar{w}_2 w_1$$

$$\bar{t}_2 = \bar{w}_3 w_2$$

$$\bar{t}_3 = w_3$$

$$y_0 = \bar{t}_1 + \bar{t}_3$$

$$y_1 = \bar{t}_2 + \bar{t}_3$$

$$z = t_0 + \bar{t}_1 + \bar{t}_2 + \bar{t}_3$$